$\underbrace{Matthew~Strong}_{720-626-4057 \mid mastro1@stanford.edu \mid \underline{linkedin.com/in/matthewhstrong} \mid \underline{github.com/peasant98}$

Education

Stanford University PhD in Computer Science, Artificial Intelligence. Advisor: Monroe Kennedy, Jeannette Boi University of Colorado Boulder Participante de la constante de	hg Stanford, CA Sep 2023 – present Boulder, CO
Bachelor of Science in Computer Science, Chinese Minor, 4.00 GPA	Aug. 2017 – May 2021
 EXPERIENCE Robotics/AI PhD Researcher, ARMLab - Stanford University ARMLab, Advised by Monroe Kennedy and Jeannette Bohg PhD researcher in the Assistive Robotics and Manipulation Lab conducting research of the state of the sta	September 2023 – present Stanford, CA on dexterous robot
 Building on top of the DenseTact sensor for perception and autonomy. Integrated visu Gaussian Splatting. Performing research on EEG-assisted robot manipulator control in Human-Robot Integrated visu 	ual-tactile data into 3D eraction.
Software Engineer - Customer Experience Platform (CXP) Septer Microsoft • Engineered AI-based solutions to improve the customer journey experience	ember 2021 – August 2023 Redmond, WA
 Designed, developed, and deployed the consent for channel optimization feature for CI Developed Holdout for A/B test experimentation. 	XP.
 Undergraduate Researcher - CU Boulder SBS Lab Sustainable Buildings and Systems Lab, Advised by Wangda Zuo Developed an automatic energy building simulation pipeline for testing energy outputs in different climate zones. 	January 2018 – present Boulder, CO s of different building models
 Devised multiple methods of building energy prediction with Generative Adversarial N Core contributor of an open source release of 500+ EnergyPlus building models, supportincluding NREL and Oak Ridge National Lab, as the culmination of a 4+ year researched sector of the sector	Networks. orted by researchers at labs ch project.
 Undergraduate Researcher - HIRO Group Jather HIRO (Human Interaction and RObotics Group) Group, Advised by Alessandro Roncone Devised a novel kinematic calibration algorithm to estimate the pose of a novel sensor Validated on a real robot control example. Proposed a framework for bridging the gap between avoidance and contact, informed collaborative robotics. Constructed an effective method for probabilistic fusion of external depth data and on reduce occlusions in a robot's nearby space. 	nuary 2020 – September 2021 Boulder, CC unit on a robot manipulator. by onboard sensors for board proximity data to
 Software Engineer Intern - Journey Optimization using RL Microsoft, Customer Experience Platform (CXP) Deployed a real-time analytics service for retrieving customer data. Designed and developed a feature from scratch called journey optimization, which interthrough the "customer journey", using reinforcement learning. 	May 2020 – August 2020 Remote - Broomfield, CO elligently guides a customer
 CTO and Co-Founder - Udana Systems Udana Systems Co-Founded company targeted towards drone delivery for small to medium sized busin Designed and developed robotics tech stack, using ROS, MavROS, Gazebo, PyTorch, Developed machine learning pipeline for computer vision based models. 	February 2018 – May 2020 Boulder, CO nesses. and more.
Software Engineer Intern - Global Search Microsoft, Dynamics 365 for Talent	May 2019 – July 2019 Redmond, WA

- Designed and developed the Global Search feature for Microsoft Dynamics 365 for Talent.
- Worked with .NET, Angular, and XML in order to successfully deploy an end-to-end feature.

National Science Foundation Graduate Research FellowshipReceived prestigious NSF GRFP for my PhD studies at Stanford.	April 2024
 Microsoft Special Stock Award The most prestigious bonus given to employees at Microsoft. Only a few individuals we 200+ employees in my organization. 	July 2023 ere nominated out of the
RSS Inclusion FellowAccepted as an RSS (Robotics: Science and Systems) Inclusion Fellow, an expenses-parobotics researchers attending RSS.	June 2021 id program for upcoming
Chancellor's Recognition AwardAn award given to students that maintain a 4.0 GPA throughout all of college.	May 2021
Active Learning AwardAward given to outstanding students in service, professional, and research experiences.	April 2021
 College of Arts and Sciences: Class of 2021 Amazing Student For my minor in Chinese, I received an outstanding student award for the Class of 202 Arts and Sciences (1 of 30 out of 4500+ students). 	April 2021 21 in the College of Arts of
College of Engineering Research AwardOnly one other CS student from CU has received this award in its 20+ year history.	April 2021
 CRA Outstanding Undergraduate Researchers 2021 – Honorable Mention The most prestigious award for CS undergraduate researchers in North America. 	December 2020
 UROP Research Grant: Null Space Control for Collaborative Robotics Received \$1500 research grant from CU Boulder's Undergraduate Research Opportunity perform research on null space control. 	ugust 2020 – August 2021 ties Program (UROP) to
Sewall ScholarThe top merit scholarship at CU Boulder.	August 2017 – May 2021
Engineering Merit ScholarshipReceived based on high school academic performance.	August 2017 – May 2021
BOLD ScholarshipReceived diversity scholarship based on high school achievement.	August 2017 – May 2021
 National Merit Scholar Selected to receive National Merit Scholarship on basis of outstanding high school achi Given to <1% of high school seniors in the US. 	August 2017 ievement.

PUBLICATIONS

Touch-GS: Visual-Tactile Supervised 3D Gaussian Splatting

Submitted to International Conference on Robotics and Systems 2024.

Aiden Swann^{*}, **Matthew Strong**^{*}, Won Kyung Do, Gadiel Sznaier Camps, Mac Schwager, Monroe Kennedy III

SHIRO: Soft Hierarchical Reinforcement Learning

Arxiv.

Kandai Watanabe, ${\bf Matthew~Strong},$ Omer Eldar

Individualized Empirical Baselines for Evaluating the Energy Performance of Existing Buildings

Science and Technology for the Built Environment.

Yingli Lou, Yunyang Ye, Yizhi Yang, Wangda Zuo, Gang Wang, **Matthew Strong**, Satish Upadhyaya, Chris Payne

Evaluating Performance of Different Generative Adversarial Networks for Large-Scale Building Power Demand Prediction

Energy and Buildings.

Yunyang Ye, Matthew Strong, Yingli Lou, Cary Faulkner, Wangda Zuo, Satish Upadhyaya.

Volumetric Data Fusion of External Depth and Onboard Proximity Data For Occluded Space Reduction

4th Workshop on Proximity Perception in Robotics at IROS 2021.

Matthew Strong*, Caleb Escobedo*, Alessandro Roncone.

Contact Anticipation for Physical Human–Robot Interaction with Robotic Manipulators using Onboard Proximity Sensors

International Conference on Robotics and Systems 2021.

Caleb Escobedo, Matthew Strong, Mary West, Ander Aramburu, Alessandro Roncone

Self-Contained Kinematic Calibration of a Novel Whole-Body Artificial Skin for Collaborative Robotics

International Conference on Robotics and Systems 2021.

Kandai Watanabe, **Matthew Strong**, Mary West, Caleb Escobedo, Ander Aramburu, Krishna Chaitanya, Alessandro Roncone.

Enabling Close Proximity Human Robot Collaboration via Distributed, Self-Calibrating Robotic Skin

BS Thesis at CU Boulder. Committee: Alessandro Roncone, Bradley Hayes, Christoffer Heckman

Matthew Strong.

Development of New Baseline Models for U.S. Medium Office Buildings Based on Commercial Buildings Energy Consumption Survey Data

Science and Technology for the Built Environment Volume 26, 2020.

Yunyang Ye, Yingli Lou, Matthew Strong, Satish Upadhyaya, Gang Wang, Wangda Zuo.

SERVICE/LEADERSHIP

Microsoft BAP Early-in-Career

- One of the founding members of a newly revamped Early-in-Career group.
- Leader of the Dynamics 365 Early-in-Career group
- Planned events, including single-handedly starting a AMA with the Corporate Vice President of the org.

HackCU

- Led HackCU's tech team, organizing the largest hackathon in the Rocky Mountain region.
- Managed whole tech stack during 500+ person hackathon.
- Developed hacker sites and APIs accessed by thousands of people across the nation and globe.

August 2018 – May 2021

2023

• Handled 1000+ hacker applications.

Slingshot Mentor and Founding Member

• Served as a founding member for students from top high schools interested in CS at Slingshot, a **Techstars-backed startup** co-founded by students from top tech companies.

June 2020 – September 2021

January 2019 - May 2019

January 2018 - May 2018

- Organized learning sessions about robotics, research, and machine learning for high school students.
- Onboarded startups out of Y-Combinator, Techstars, Berkeley, Stanford, and more.

Discrete Structures Tutor

- Mentored student in discrete structures.
- Set homework and test-prep deadlines, and prepared practice problems.

SASE (Society of Asian Scientists and Engineers) Leadership

• Served as Co-Marketing Director and managed social media pages.

Membership

Microsoft BAP EIC Group	March 2022– August 2023
Colorado Data Science Team	August 2019 – December 2020
SHPE (Society of Hispanic Professional Engineers)	August 2019 – May 2021
SASE (Society of Asian Scientists and Engineers)	August 2017 – August 2019
Invited Talks	
HackCU Workshop Invited Speaker: An Introduction to AIGave a talk on an introduction to AI at HackCU.	March 2024
HackCU Workshop Invited Speaker: A Gentler Introduction to Robotics • Invited to conduct a workshop on how to get started with algorithm robotics a	March 2022 t HackCU.
Invited Speaker at the PhD Forum: 4th Workshop on Proximity Percept. • Only undergraduate invited to speak at the forum.	ion in Robotics August 2021
Slingshot Interview Series: Getting Involved in RoboticsInvited by Techstars-backed startup to be interviewed on my experience with r others can learn from me.	August 2021 obotics, how I improved, and what
Reviewer	

IEEE Robotics and Automation Letters (RA-L)	2023
IEEE International Conference on Robotics and Automation (ICRA)	2023
IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)	2022